

## Development of a Mixed Reality Game for Simulation Based Education

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**Abstract:** Mixed reality allows for new ways for learners to enrich their learning experience. By enabling the use of 3D virtual content in a tangible space, it offers a more immersive digital learning environment than traditional on-screen methods. This paper reports on the use of the Mixed Reality (MR) Microsoft HoloLens to create a mixed reality Vocational Educational Training (VET) serious game.

The main challenges of this investigation are the use of tangible objects as an interface to a virtual learning environment, which is achieved through low-latency, real-time tracking, allowing for believable interaction with virtual content. This is examined through the creation of a stone grinding application for training college-level stonemasons, whereby the learner attempts to cut a dogleg into a virtual stone block using a real grinder. Cyber-physical systems (CPS) are utilised to realise this as part of the digital pedagogy. Currently, the vocational training is strung by regulations which do not allow students to use a working angle grinder until training is complete. By using a virtual stone block, a tangible grinder can be held without the associated safety risks.

The application has been co-designed and developed in association with several further education colleges in Scotland and has received appraisals from teachers and learners. On-site demonstrations have been carried out, with the mixed reality operation alongside a PC-based, mouse-operated application. Early feedback has suggested that this is a system that the colleges are interested in and could provide a real use in training. This work builds upon research carried out for the BEACONING program, part of the Horizon 2020 framework.

**Keywords:** Mixed Reality, HoloLens, Cyber-physical system, VET, Simulation based education, Serious Games

## 1. Introduction

One of the most important aspects of any digital learning environment is the emulation of real-world settings. The MR VET application was developed based on a computer-based training game developed by Imaginary for the BEACONING program. The desktop application uses a mouse-based interface to carry out all the steps of a grinding procedure and can be used as a training tool to assist with learning the methodology required for stonemasonry. However, without a tangible link to the real world, the pedagogical aspects of this application may be somewhat limited, as the actual use of a stone grinder is impossible to simulate with a mouse interface. The MR application has been designed to reflect this need for more practical training.

### 1.1 The use of MR in pedagogy

In the field of pedagogy, technology can be used to assist learning in ways traditional pen-and-paper methods cannot. Currently, in the field of stonemasonry, students are unable to use working grinders on real stone due to the associated health risks. This is a vital component in day-to-day work as a modern stonemason, and the lack of prior grinding experience affects future employment prospects, as employers are reluctant to provide further training. Using MR, it can be possible to provide a believable training environment without the associated health risks, ensuring the student is as prepared as can be possible for industry.

Visualisation of concepts is a highly important part of the learning process (Tasker & Dalton, 2008), and it has been found that it can be difficult to teach these concepts and processes without visible models upon which the students can base their knowledge. The use of MR brings this visualisation into the real world, and allows the concepts to be explored within a familiar environment.

Some work has been carried out into the use of MR in medical training (Cowling & Birt, 2018). It was found that student outcomes and skill development had been enhanced by the simulation. However, the article also stresses the importance of “pedagogy before technology”, meaning that placing the training experience offered ahead of the technology used was vital in ensuring the training provided was worthwhile.

### 1.2 Serious games in the construction industry

Some prior work has been carried out into the viability of a cyber-physical gaming system in the construction industry (Sivanathan, et al., 2014). The system devised was a ladder climbing activity. By attaching sensors to the participant, it was possible to monitor the movements and posture of the activity. The system then delivered a score depending upon how successful the task was (good posture, for example). Another advantage of this style of cyber physical system was the instantaneous feedback, represented in a virtual form. It was found that such a system enhanced the quality and delivery of training.

This system has influenced the development of the MR VET game, with the aim of providing real time feedback as well as meaningful feedback after the operation has been completed. Future work for this project includes attaching sensors to the participant and grinder for further analysis purposes.

### 1.3 Gamified Lesson Planning

Gamified lesson planning is a major outcome of the BEACONING program (Morini, et al., 2015). Successful VET depends largely on experience, and hands-on experience is vital to successful learning. A gamified lesson can be used to show competency and knowledge transfer in the ability to apply material that has been learned in the classroom. To this end, it is important to ensure the game has been mapped around achieving a primary objective. The game should not be an aside to the main pedagogy, instead it is one of the steps to a learning outcome.

## 2. VET Game

The HoloLens application makes use of CPS and Human-in-Loop (HIL) to provide an immersive learning experience that reflects real world working conditions as much as possible. To achieve this, the game makes use of image-based tracking and gesture control. To ensure the game is a useful learning tool, it has been developed within guidelines for VET from National Occupational Standards (Scotland).

### 2.1 Game flow

The game flow is illustrated in Figure 1.

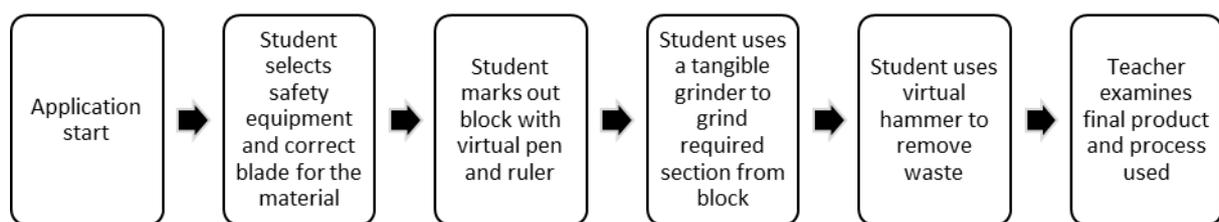


Figure 1: Game flow diagram

#### 2.1.1 Game mapping

The VET game is mapped to National Occupational Standards COSVR195 (National Occupational Standards, 2017). This is outlined in Table 1 and Figure 2.

Table 1: Mapping to Occupational Standards

Participants	Location(s)	Resources	Evidence	Rewards
Students	Anywhere	Mixed Reality, CPS	COSVR195 P1-P6, K1-K16	Experience with an angle grinder, increased employability

**COSVR195**  
Produce standard architectural stone enrichments

**Performance criteria**

- You must be able to:*
- P1 interpret the given information relating to the work and resources to confirm its relevance
  - P2 comply with the given, relevant legislation and official guidance to carry out your work and maintain safe work practices
  - P3 select the required quantity and quality of resources for the methods of work
  - P4 comply with organisational procedures to minimise the risk of damage to the work and surrounding area
  - P5 comply with the given contract information to carry out the work efficiently to the required specification
  - P6 complete the work within the allocated time, in accordance with the programme of work

**Knowledge and understanding**

*You need to know and understand:*

**Performance Criteria 1**

**Interpretation of information**

- K1 the organisational procedures developed to report and rectify inappropriate **information** and unsuitable **resources**, and how they are implemented
- K2 the types of **information**, their source and how they are interpreted
- K3 the organisational procedures to solve **problems** with the **information** and why it is important they are followed

**Performance Criteria 2**

**Safe work practices**

- K4 the level of understanding operatives must have of **information** for relevant, current **legislation and official guidance** and how it is applied
- K5 how **emergencies** should be responded to and who should respond
- K6 the organisational **security procedures** for tools, equipment and personal belongings
- K7 what the accident reporting procedures are and who is responsible for making the report
- K8 why, when and how **health and safety control equipment** should be used

*You need to know and understand:*

**Performance Criteria 3**

**Selection of resources**

- K9 the characteristics, quality, uses, sustainability, limitations and defects associated with the **resources** and how defects should be rectified
- K10 how the **resources** should be used and how any **problems** associated with the **resources** are reported
- K11 the organisational procedures to select **resources**, why they have been developed and how they are used
- K12 the **hazards** associated with the **resources** and **methods of work** and how they are overcome

*You need to know and understand:*

**Performance Criteria 4**

**Minimise the risk of damage**

- K13 how to **protect work** from damage and the purpose of protection
- K14 why **disposal of waste** should be carried out safely and how it is achieved

*You need to know and understand:*

**Performance Criteria 5**

**Meet the contract specification**

- K15 how **methods of work**, to meet the specification, are carried out and **problems** reported
- K16 how **maintenance** of tools and equipment is carried out

*You need to know and understand:*

**Performance Criteria 6**

**Allocated time**

- K17 what the **programme** is for the work to be carried out in the estimated, allocated time and why deadlines should be kept

*You need to know and understand:*

**Figure 2: COSVR195**

Mapping the application to COSVR195 (Figure 2) ensures it will be a useful tool for the pedagogical aspect of VET. The performance criteria ensure that basic competence is achieved during training, whilst the knowledge and understanding components develop the correct working attitudes. It is important that the VET game reinforces both sections, so the game has been designed around testing as many of these aspects as possible.

**2.2 Components of the game**

The basis of the game is to replicate a real-life stonecutting operation, using a real grinder on a virtual block, to provide a training experience that cannot be obtained through purely practical means. This involves wearing the correct Personal Protective Equipment (PPE), marking out the desired cut with a ruler and pen, cutting the block using the grinder and removing the waste with a hammer.

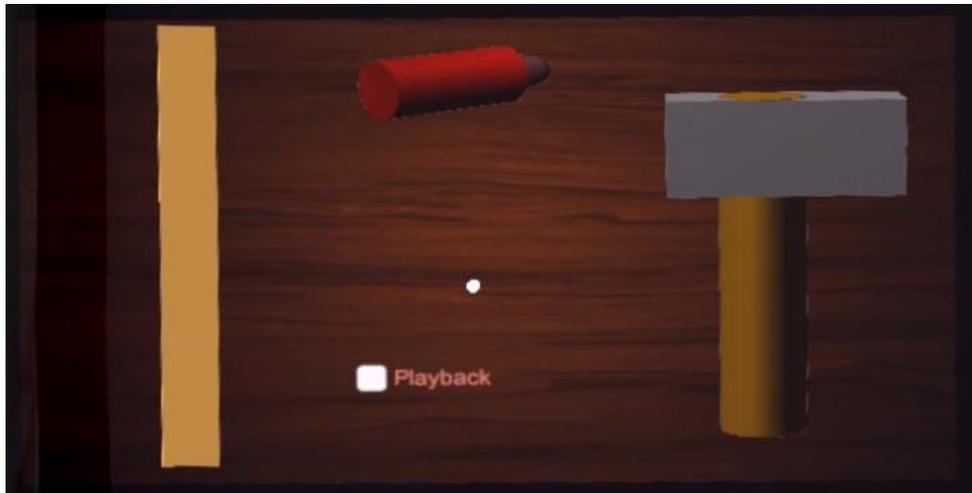
**2.2.1 PPE selection**



**Figure 3: PPE Selection Interface**

One of the top priorities with VET is to instil the proper safety procedures (see P2 in Figure 2). To this end, a simple, image-based checklist is present to ensure all the correct PPE is equipped (respirator, goggles, safety gloves, ear defenders, safety boots and helmet).

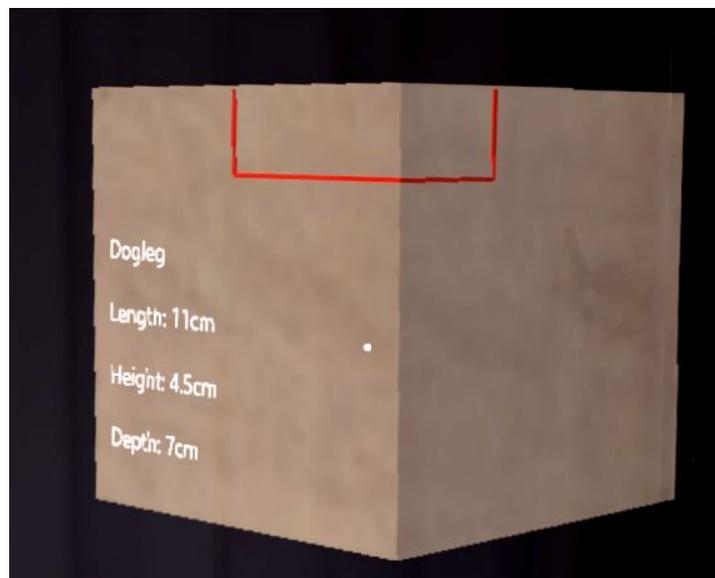
### 2.2.2 Tool Selection



**Figure 4:** Tool Selection Interface

To ensure that the user will have access to all the required virtual tools (ruler, pen and hammer) with ease, a toolbox is placed in the world space. Selecting a tool from this box will cause it to appear in front of the user. The “Playback” button shows a replay of the cutting process once toggled.

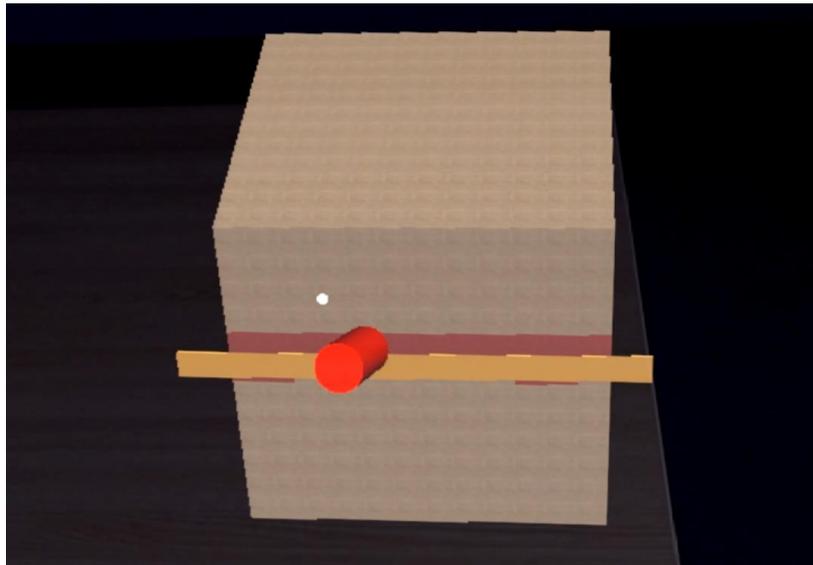
### 2.2.3 Mission display



**Figure 5:** Mission display

The mission display is a 1:1 representation of the stone block, with dimensional information and the type of shape required.

#### 2.2.4 Marking Out



**Figure 6:** Marking out with a pen and ruler

As the block is virtual, the marking out of the cut is performed using a virtual pen and ruler using HoloLens' gesture controls, demonstrated in Figure 6. The manipulation of these objects are performed using gesture commands. The ruler uses a "tap to place" mechanism whereby once tapped, the ruler follows the user's gaze and "snaps" on to any gazed object. The pen uses a "hand dragging" mechanism whereby the user gazes at the pen, taps it and manipulates it using their hand. As the pen and the hand are not actually interfacing, a control-display gain value (Casiez, et al., 2008) is used to approximate the user's hand movements into pen movements. This builds upon research previously carried out into control-display gain in a mixed reality environment (Harper, et al., 2018).

#### 2.2.5 Grinding

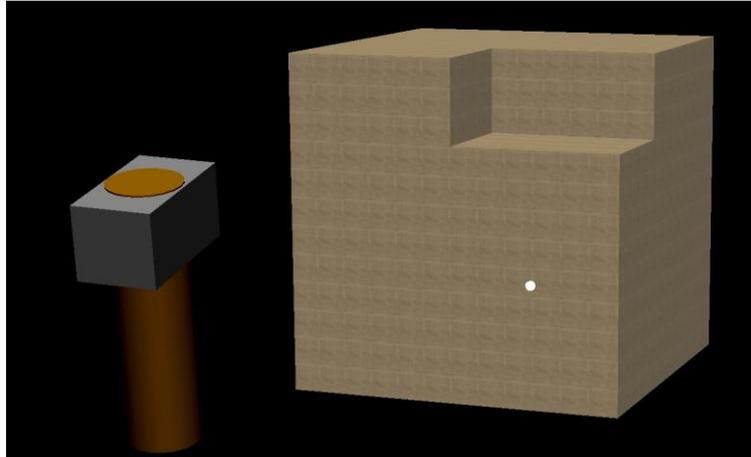
*As of the time of this report, the HoloLens does not support taking a screenshot whilst Vuforia is active.*



**Figure 7:** Grinder with image target (left) and grinding stone (right)

Using Vuforia's image-based tracking, a tangible grinder is used to cut into the virtual stone block. The image target was trialled in numerous positions, it was determined that placement on top of the blade allowed for the largest operating range before the target disappears from camera view and tracking ceases to operate. Real grinding operations produce physical vibration in the grinder, which cannot currently be replicated, however other aspects such as dust and sound are reproduced to provide some tangible feedback to the operator. This is also where the chosen grinding blade comes into effect, as an incorrect choice of blade for the stone will cause the grinder to fail.

### 2.2.6 Waste Removal



**Figure 8:** Waste removal with virtual hammer

The final step in the stonecutting process is waste removal. This is simplified in the application to the use of a virtual hammer to remove the cut-out portion of the block. The hammer uses the same "hand dragging" input system as the pen.

### 2.3 Teacher use

As well as the output of the application, teaching staff have control over the application parameters through the BEACONING service. The teacher can control the type of stone used and the cut required, which is read by a .JSON file in the application. The application tracks parameters of the usage and stores them in another .JSON file. This file can then be opened in the BEACONING service, allowing the teacher to analyse the placement of the cut, as well as the usage of safety equipment. It is also possible to record a replay of the session for teacher playback.

### 2.4 Implementation

As previously mentioned, the Microsoft HoloLens was chosen as the operating device for this application. It has unique advantages that have been utilised in this study. The main advantage for operation in VET workshops is that it is completely self-contained; no other equipment is required to operate it as all processing and rendering is carried out on the device itself, as opposed to immersive headsets such as the HTC Vive or Oculus Rift. Another key advantage is the onboard cameras, which allow for the image-based tracking, and the translucent screens which allow the holograms to be placed in the real world.

The device runs a modified, 32-bit version of Windows 10, similar to that found on Windows phones, and exclusively uses Universal Windows Platform (UWP) applications.

Storage	64GB Flash
RAM	2GB
CPU	Intel custom 32-bit Atom processor with TPM 2.0 support plus separate Microsoft Holographic Processing Unit (HPU)
Graphics Processor	Intel integrated graphics
Holographic resolution	2.3 million total light points
Field of View	16 degrees
Display resolution	1268 x 720 per eye at 60Hz (240Hz over red, blue and two green layers)
Sensors	1 IMU, 4 environment understanding cameras, 1 depth camera, 1 2MP photo/720p video camera, 4 microphones, 1 ambient light sensor
Connectivity	3.5mm audio jack, Wi-Fi, Micro USB 2.0, Bluetooth 4.1 LE

**Table 2:** HoloLens specifications

The application was developed on an HP Compaq 8200 Elite CMT PC. The specifications are as follows:

CPU	Intel Core i7-2600
Memory	16GB DDR3, 1333MHz
Storage	2 x 500GB HDDs with 4 partitions
GPU	Nvidia Quadro 4000
Operating System	Windows 10 with Fall Creators Update, 64-bit

**Table 3:** Development PC specifications

The development environment used was Unity 2017.3.1p1, in C#, utilising the Mixed Reality Toolkit provided by Microsoft on GitHub (Microsoft Corporation, 2018) to integrate HoloLens specific functionality. The Vuforia plugin was included to perform the image based tracking for the grinder. The applications are built on the PC and deployed to the HoloLens over a LAN connection. Unity was chosen for the development process due to its ability to produce 32-bit UWP applications, as well as its ease-of-use, extensive documentation, and support for the HoloLens and Vuforia.

### 3. Findings

It is challenging to quantify the effectiveness of training without resorting to subjective measures such as questionnaires. To acquire data on the use of a VET game, a focus test was carried out at Glasgow College. These involved students and their teachers making use of both the computer-based VET game and a prototype MR version. From these tests, the participants were asked to complete a simple dogleg cut in the computer game and given no further instruction, to gauge the quality of the in-app instructions and the intuitive-ness of the controls and interface. After completing this task, a standard BEACONING questionnaire was filled out and the results collated.

#### 3.1 Questionnaire Results

The survey was carried out with a class of eight second year Stonemasonry students, and a separate one with four teachers was also performed. The questions asked to students that were relevant to the VET game were as follows:

1. What styles of games the students would want to play in a class (co-operative, competitive, quizzes, etc.)
2. Difficulty rating of the game.
3. Level of excitement generated by the game.
4. How much various aspects of gamification motivated them to carry out their tasks (leaderboards, progress bars, classroom comparisons, etc.).
5. How much various aspects of gamification would motivate them to carry out their tasks in STEM subjects
6. What feedback was expected from the game.

From the student questionnaire, it was found that most students would like to play simulation type games in class. Feedback on difficulty was split exactly in half between the game being at a suitable level of difficulty and being too easy. The consensus on excitement was that the game was neutral, neither generating excitement or boring. In terms of motivation in the game, results indicated that the most motivating factor would be the rewards for completion, which potentially include course credits. Motivation for STEM subjects showed that the subject of the lesson was the most motivating factor, along with the inclusion of minigames. Finally, the most valuable feedback expected from the game was reasons for why any answers given were correct or incorrect.

The teachers survey contained the following relevant questions:

1. What components of a lesson plan need to be adjustable (difficulty, length, etc.)
2. How to tailor the lessons towards students with special needs
3. What data to consider for student assessment
4. If they think the students enjoyed playing the VET game

In terms of adjustable components, the teaching staff unanimously wanted control over the length and difficulty of the game. For tailoring to special needs students, again the difficulty was unanimously requested along with specially formulated task descriptions. For student assessment purposes, the teaching staff unanimously requested access to the number of attempts made and the difficulty of the task. Finally, the teaching staff unanimously “strongly agreed” that the students enjoyed the gamified lesson.

### **3.2 Discussion of Results**

Acquiring feedback from both student and teacher points has allowed for a useful comparison between what the students think is important, and what the teachers want the students to do. Despite these results being generated from a questionnaire focussed on the desktop VET game, as there are common points across the desktop and MR based games it is still possible to gain some useful insight from these surveys.

Some of the feedback generated from the questionnaires was a reassurance that VET in a gamified environment is possible and what the students and teachers want to see. Staff agreed that students enjoyed the lesson, and students showed interest in the simulation type of game that was on offer, and that it related to their course content.

Difficulty was a repeating point raised, by both teachers and students. To this end, it is important for the VET game to have a mission selection of some variety, and this has been implemented currently in the form of a choice of stone and premade cuts, and in future a choice of cut shape and depth will also be implemented. It would be possible for different students to run different levels of difficulty, as the mission selected is recorded in the .JSON file output from the application.

At the time of the on-site test, the MR app was still in a prototype stage, with no support for a tangible grinder and some interface and performance issues, so only anecdotal feedback was taken for further application development. This led to the creation of the toolbox for tool selection, the free placement and rotation of the block and the simplifying of gesture controls in the game. Further testing is to be carried out very shortly with the current, improved version of the application, complete with image-based tracking.

## 4. Future Work

To make the application fully viable for public use, some further work will be required. The main issues with the application in its current state are: usefulness of results, grinder tracking, and rendering performance.

As is, the results are images of the cuts, an on-device replay, and a checklist of safety equipment and blade used. Images of the marking out should also be taken. The replay should either be viewable on other devices (such as a PC) or saved to the device for later viewing. This could involve the use of a proxy application on a PC to allow free camera movement and pause functionality to analyse the procedure used by the student. For quick reference amongst a class of students, it would be useful to have a sort of scoring functionality for the quality of the marking and cut in comparison to the mission that was provided.

Whilst Vuforia's image tracking is effective for horizontal cuts, it can prove impractical for vertical cuts due to the requirement of keeping the image target within camera shot. The solution for this will be to use accelerometers connected to the grinder, which are connected over TCP to the HoloLens. Interpreting the output from the accelerometer will allow for cutting even at angles where the blade is not visible.

Another issue with the application is one of performance, namely the frames per second (FPS) output by the device. As the application uses a "voxel" system to allow for cuts and drawing on the surface (the stone block is made up of hundreds of smaller cubes), the FPS will drop from the optimal 60FPS target when the block is in view, as the application becomes GPU-bound. One solution for this is the use of a façade block, with the voxels hidden and not rendered within, only to be rendered when the hammer strikes the block to remove material. This reduces the rendering load of the application, increasing the FPS performance towards the target.

## 5. Conclusions

This study shows the use of a Mixed Reality system to deliver a novel vocational educational training application for stonecutters, building upon the previously produced desktop game. The use of a real stone grinder is positive from the aspects of pedagogy and health and safety, as proper handling can be instilled before day-to-day use in industry. Ensuring the pedagogy is carried out in a real-world environment increases the pedagogical aspect of the application, by allowing visualisation of the concepts learned in class. Collaborating with further education institutions has allowed for implementation of features that the teachers and students want to see. Mapping the application to National Occupational Standards also ensures the game has real learning value, for both operational competency and safety.

### 5.1 Acknowledgments

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